

## Chapter D20

### Bearing mistakes to avoid



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Individual chapters of the Kalsi Seals Handbook™ are periodically updated. To determine if a newer revision of this chapter exists, please visit <https://www.kalsi.com/seal-handbook/>.

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## 1. What is this chapter doing in a rotary seal handbook?

Rotary seal implementation requires a systems approach to equipment design, which is why this seal handbook exists. If equipment design is not appropriate, then seal performance will not be optimal.

Bearings are one of the most important elements in a piece of rotary equipment. For example, in a sealed bearing mud motor, the bearings react the enormous drilling thrust load to the drillstring, guide the drill bit, and guide the shaft that the rotary seals run against. Seal abrasion and extrusion resistance suffers when the bearings cannot do their job properly. The role of the rotary seals is to protect the bearings, and if the bearings fail due to faulty bearing implementation, then the customer may incorrectly place blame upon the seals. For this reason, we have more than a passing interest in helping our customers implement their bearings properly. This chapter is not a comprehensive guide to bearing implementation, but it will help you to avoid several serious mistakes. Don't let a faulty bearing arrangement torpedo your seal implementation.

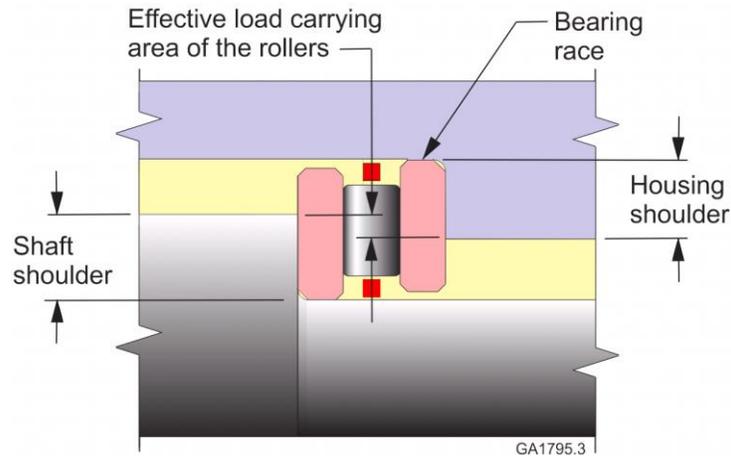
## 2. Inadequate thrust bearing support

Thrust bearing shoulders should fully support the rollers. Failure to fully support the rollers greatly reduces bearing load capacity, and leads to premature roller damage.

Figure 1 provides an example of an improperly supported thrust bearing. The housing and shaft shoulders are too small to provide complete support to the races, and the load is borne primarily by the central part of the rollers. If subjected to heavy loads, the central part of the rollers may receive damage. Severe shock loads may cause brinelling (Figure 15), and subsequent operation may cause spalling. The spalling will contaminate the lubricant with metal particles, which is a less than optimum situation for the rotary seals. Eventually the bearing will fail altogether, causing significant component and rotary seal damage. The root cause may be difficult to diagnose amidst the destruction: Was it a bearing failure or a rotary seal failure? Avoid this problem by providing adequate thrust bearing support. Figure 2 shows a roller from a mud motor thrust bearing that operated only 50 hours with inadequate support.

Two actions can rectify the problem depicted in Figure 1:

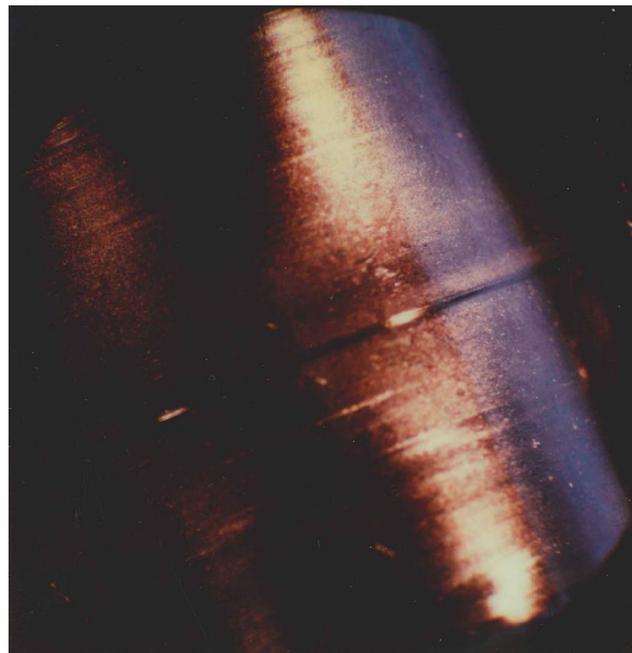
1. Increase the housing and shaft shoulder areas, or
2. Provide adequately thick backup washers.



**Figure 1**

**Inadequate thrust bearing support**

If heavily loaded, this thrust bearing may fail prematurely due to inadequate support. To establish proper support, use bigger housing and shaft support shoulders, or backup washers.



**Figure 2**

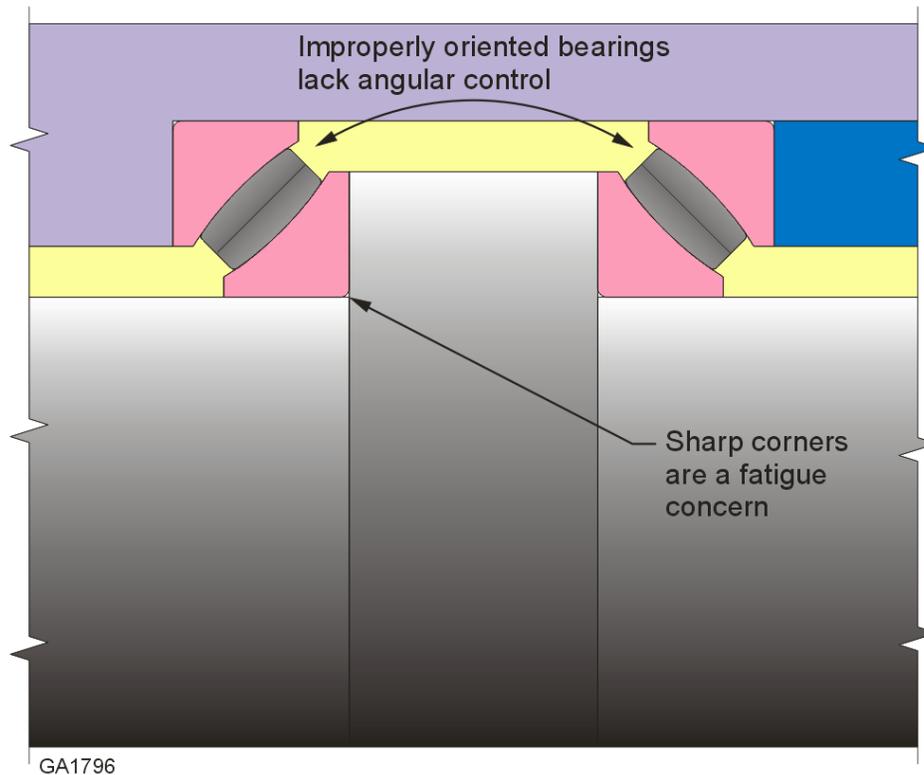
**A thrust bearing roller that operated with inadequate support**

Due to inadequate support of the bearing race, the center of this mud motor thrust bearing roller suffered damage after only 50 hours of rotation at a shaft speed of 250 rpm. Providing adequate backup washer thickness cured the problem.

### 3. Spherical roller thrust bearing orientation

In the implementation shown in Figure 3 (fixed shaft shoulder), spherical roller thrust bearings provide practically no angular control of the shaft. Instead, they function in a manner similar to a ball joint. If such a bearing implementation is set up; to guide the shaft, then the result will be gross runout, metal-to-metal contact between the shaft and the outer housing, and rapid failure of the rotary shaft seals.

Even oppositely implemented (fixed housing shoulder), spherical roller thrust bearings can tend to provide relatively imprecise radial control of the shaft. For example, bearing end play causes radial clearance, allowing excessive radial shaft motion. Spherical roller thrust bearings are not well suited for high axial shock loads, due to the relative fragility of the typically-sized thrust shoulder on the inner race.



**Figure 3**

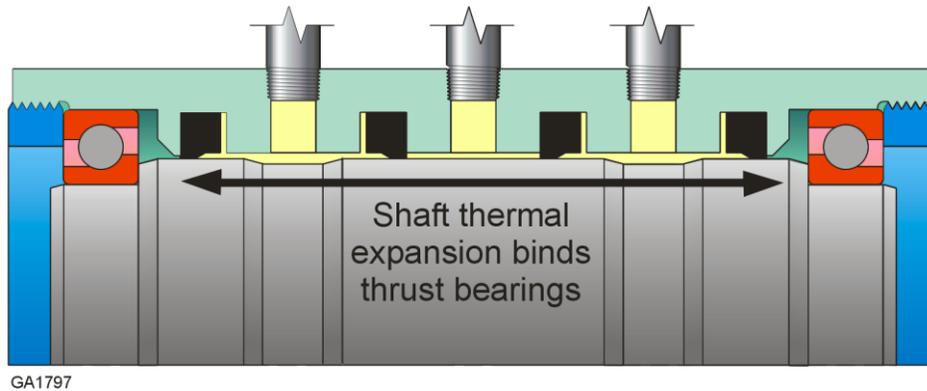
**This orientation provides virtually no angular control**

In this orientation (fixed shaft shoulder), spherical roller thrust bearings provide very little angular control of the shaft.

#### 4. Thermal binding of thrust-capable bearings

In Figure 4, the shaft absorbs the seal generated heat, causing the shaft to thermally expand more than the bearing housing. Such differential thermal expansion between the shaft and the housing can grossly overload and rapidly destroy the bearings. Do not position thrust-capable bearings far apart from one another if the shaft can become hotter than the bearing housing.

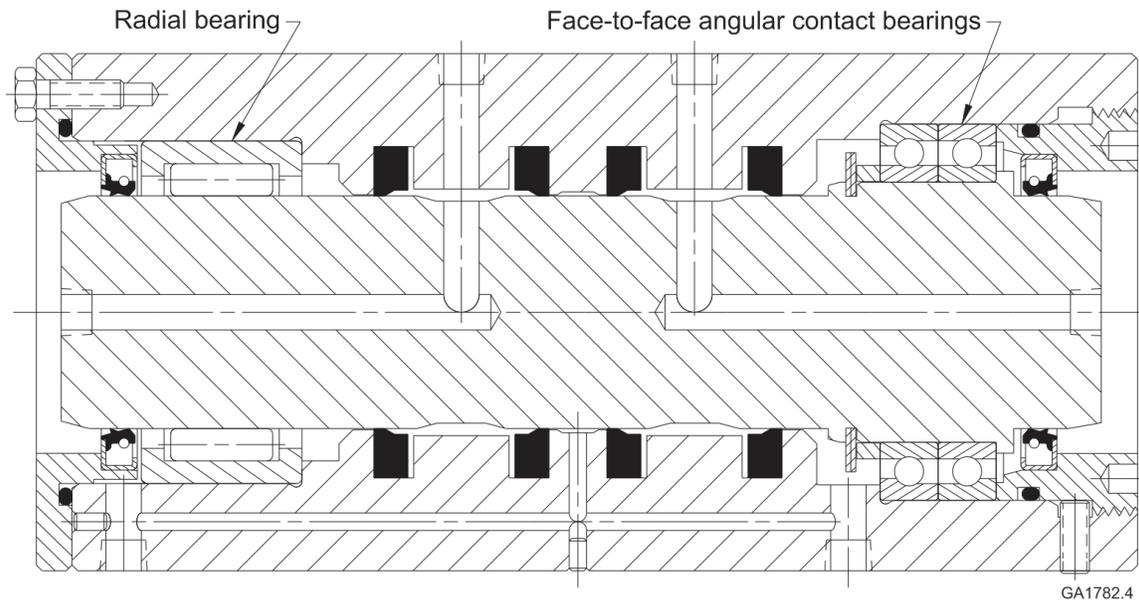
As Figure 5 shows, positioning the angular contact bearings (that locate the shaft axially) close together makes them immune to axial differential thermal expansion between the shaft and housing. The radial bearing at the opposite end of the shaft has no thrust capacity; therefore, axial shaft thermal expansion cannot overload it. Although the left-hand bearing in the illustration is a roller bearing, a ball bearing – with one race installed with a slip fit, and the other with a press fit, per normal bearing fitting practice – will achieve the same effect.



**Figure 4**

#### **Differential thermal expansion can destroy thrust-capable bearings**

The angular contact bearings shown in this hydraulic swivel are too far apart. The shaft will thermally expand more than the housing due to seal and bearing generated heat. Due to the high modulus of elasticity of the shaft and housing, the thermal expansion will overload and destroy the bearings. As a result of the bearing failure, the Kalsi Seals® will be unable to perform satisfactorily as hydraulic swivel seals.



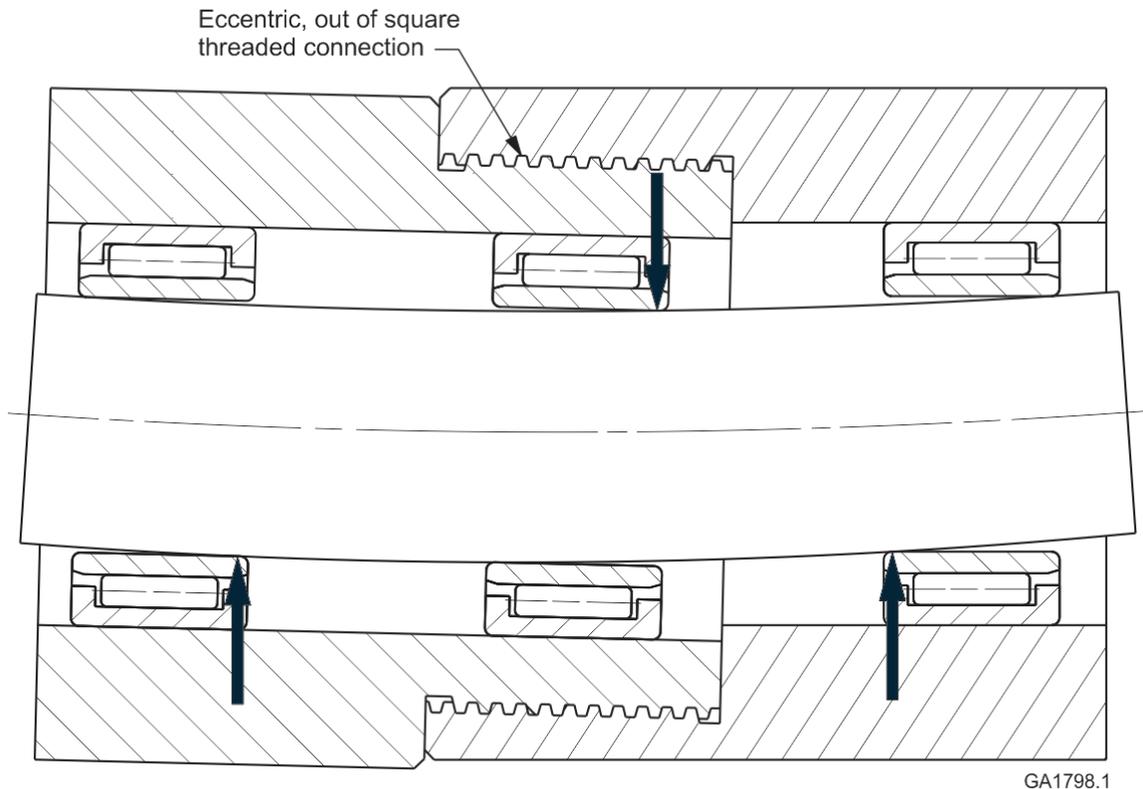
**Figure 5**

**Accommodating axial thermal expansion of the rotary shaft**

In this hydraulic swivel sealing arrangement, the thrust-capable angular contact bearings are close together, and the radial bearing at the opposite end of the shaft has no thrust capability. Axial differential thermal expansion between the shaft and the housing will not overload the angular contact bearings because they are next to each other. The angular contact bearings are shown in a “*face-to-face*” arrangement, to minimize resistance to moments. This helps to prevent the angular contact bearings from binding with respect to the left-hand if the bearing mounting bores in the housing are eccentric with respect to one another.

**5. Over constraint of radial bearings**

The exaggerated schematic of Figure 6 illustrates the effects of incorporating too many radial bearings in misaligned threaded housings. The amount of eccentricity and/or angular misalignment between the housings is causing an offset that exceeds the rather minute bearing clearance. This situation, called “over constraint,” causes bearings to fail prematurely, because of gross overloading due to the stiffness of the shaft. The same situation can occur with journal bearings. Eliminating the middle bearing can reduce the risk of over constraint.



**Figure 6**  
**Shaft over-constraint**

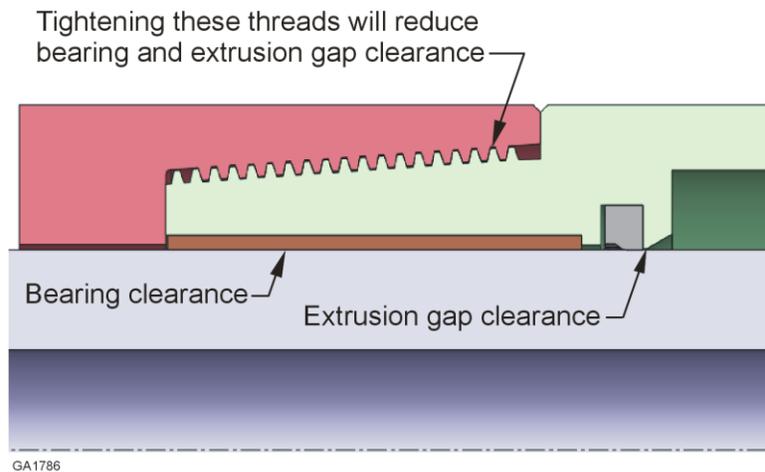
In this exaggerated schematic, thread eccentricity and shoulder misalignment are binding the shaft. This will result in bearing overload, and premature failure.

## 6. Thread-induced binding

In Figure 7, the radial bearing and rotary seal are close to a tapered “box and pin” type threaded oilfield connection. Tightening such connections to very high torque values ensures that the connecting remains tight in downhole service. A radial component of the thread tension causes the pin to elastically deform inward. The magnitude of deformation can easily cause the bearing to bind with respect to the rotary shaft, and may cause the extrusion gap of the rotary shaft seal to drag against the shaft. The result will be rapid bearing and seal destruction.

When using such threaded connections, analyze the deformation, and design around it. The preferred workaround is to position bearings and seals far enough from the threads so that thread-induced elastic deformation does not affect them. In some cases, this is simply not possible. For example, in mud motors, it may be necessary to position a threaded connection around a radial bearing in order to keep the tool as short as possible.

In such cases, it may be preferred to apply light torque to ensure shoulder-to-shoulder contact, and then finish tightening with controlled angular makeup, instead of controlled torque. This method provides controlled deformation of the threaded part of the seal carrier, because the stress and deformation resulting from tightening are not influenced by variations in thread and shoulder friction.



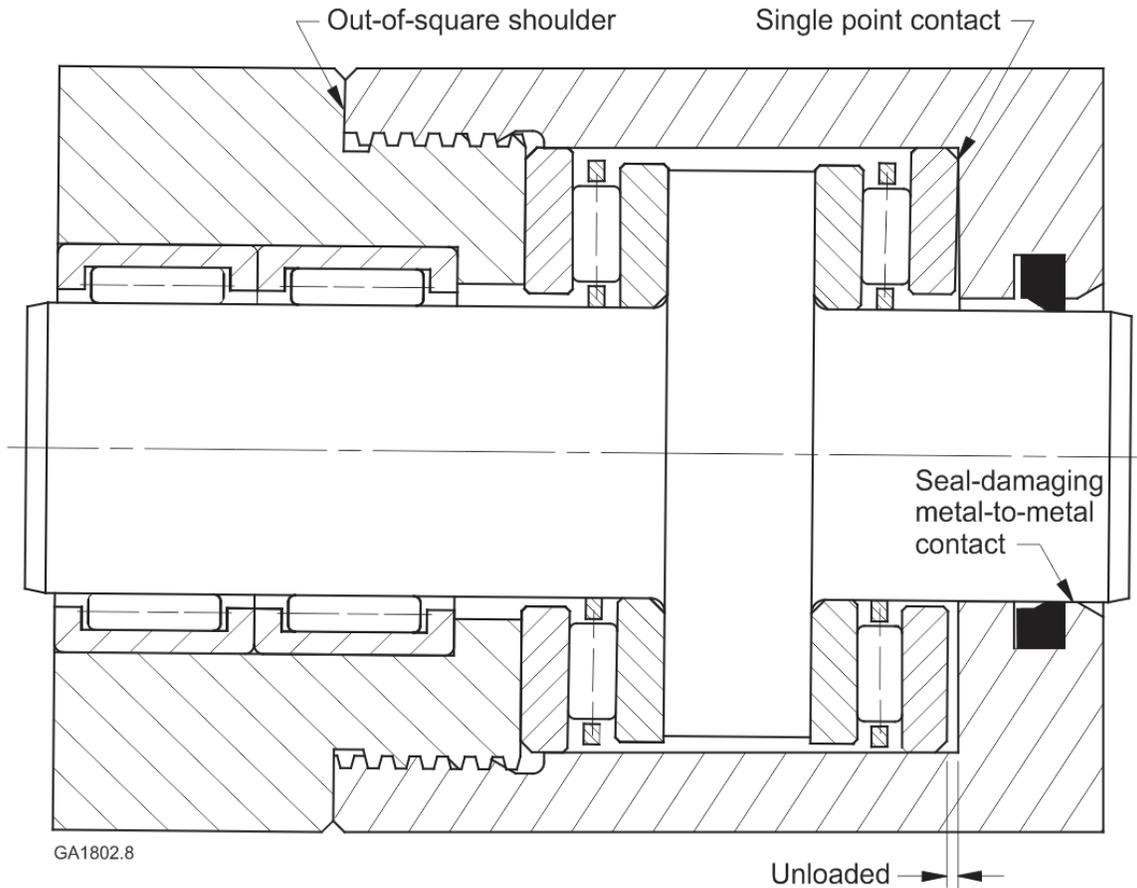
**Figure 7**  
**Thread-induced binding**

With tightening of the mud motor threaded joint shown here, a component of the resulting thread tension causes the male threaded member to elastically deform in the inward radial direction. This deformation can bind the journal bearing against the shaft, and may cause the extrusion gap bore to rub on the shaft. Such deformation-induced contact can destroy the bearing and the rotary shaft seal.

## 7. Thrust bearing misalignment

In the exaggerated schematic of Figure 8, an out-of-square shoulder causes the shaft to angularly misalign with the right-hand housing. This misalignment causes non-uniform bearing support. While there can be various causes of angular shaft misalignment, if heavy thrust loads are present, then shortening of the thrust bearing life can result.

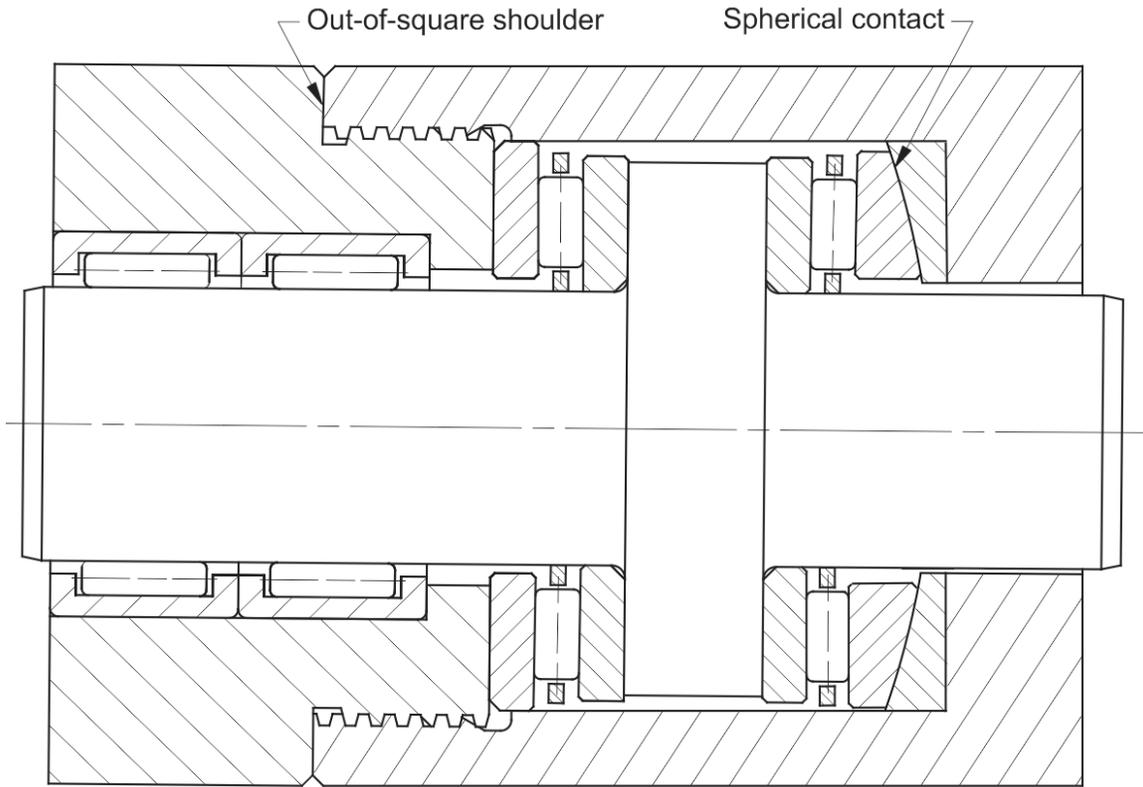
One commercially available cure for static misalignment is a two-piece self-aligning race arrangement, where the interface between the two race components is spherically ground (Figure 9). Bearing manufacturers do not recommend such arrangements for service conditions with continually changing alignment.



**Figure 8**

**Angular misalignment shortens thrust bearing life**

As shown by this exaggerated schematic, angular shaft misalignment causes uneven thrust bearing support. This situation causes significantly shortened thrust bearing life, especially if heavy thrust loads are present. Out-of-square shoulders comprise one potential cause, among several, for angular misalignment.



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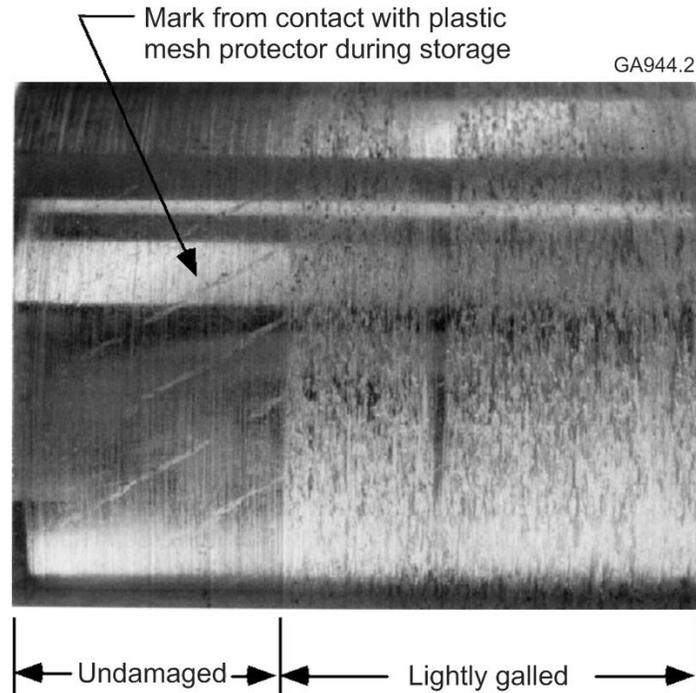
**Figure 9**

**A self-aligning washer accommodates static misalignment**

As shown by this exaggerated schematic, the spherical interface of a two-piece self-aligning race arrangement accommodates static misalignment. (Not recommended for service conditions that have continually changing alignment.)

### 8. Bearing mounting fit

With bearings that have two races, the typical practice is to provide an interference fit for the race that has relative rotation with respect to the load. Consult your bearing manufacturer’s literature for fitting practices. Failure to provide an interference fit on the correct race can lead to race slippage and wear of bearing mountings surfaces (Figure 10). This wear can potentially put metal particles into the lubricant, which can damage the bearings and rotary shaft seals.

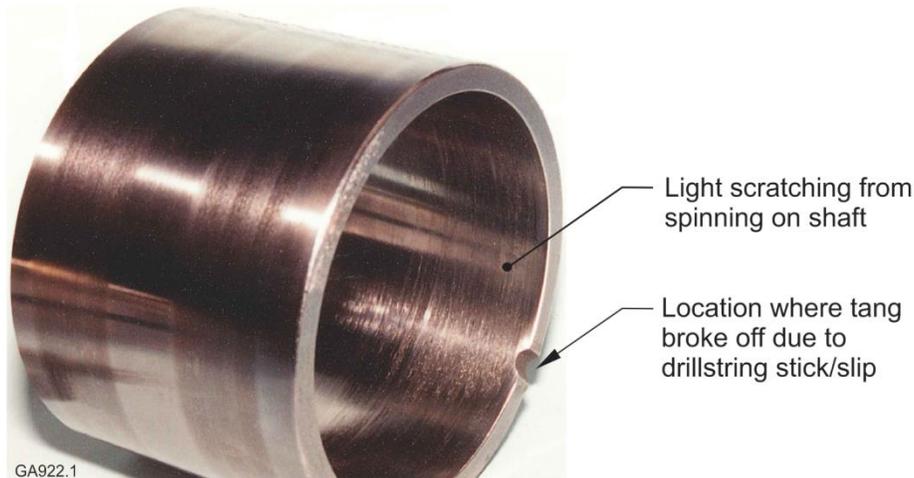


**Figure 10**

#### **Failure to press fit the race that has relative rotation with the load**

Bearing race slippage galled this shaft of an oilfield downhole drilling tool. The race was a slip fit, and had a tang intended to cause the race to rotate with the shaft. Angular acceleration due to drillstring stick/slip<sup>1</sup> caused tang failure (Figure 11), allowing the hardened race to slip on the shaft. The resulting slippage galled the EN 30B – BS 970 grade 835M30 alloy steel shaft.

<sup>1</sup> For information on stick/slip, see SPE Paper No. 145910, "Drill Pipe Measurements Provide Valuable Insight into Drill String Dysfunctions".



**Figure 11**

**Evidence of angular acceleration due to drillstring stick/slip**

This race caused the galling shown in Figure 10. The undersized tang, intended to cause the race to rotate with the shaft, failed due to drillstring stick/slip.

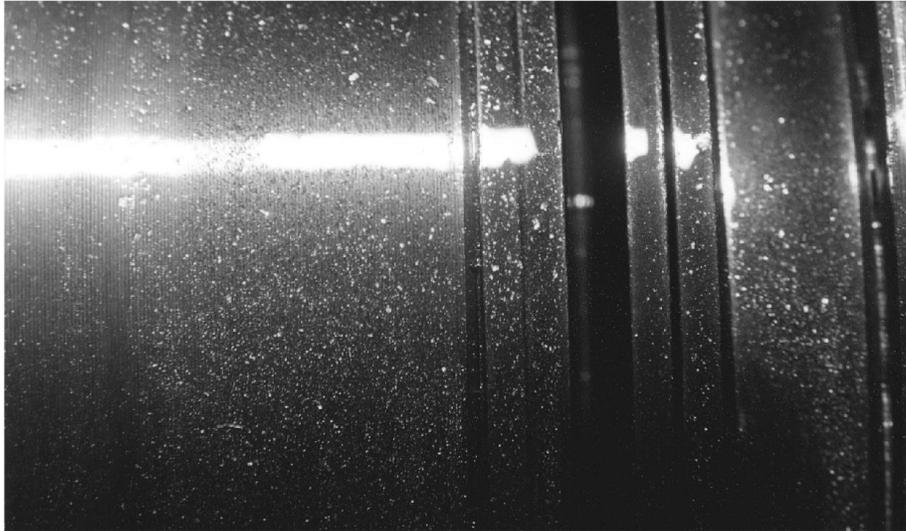
## 9. Drillstring angular and axial acceleration

Oilfield mud motors and rotary steerable tools are subject to extreme angular and axial accelerations due to drillstring elasticity and length<sup>2</sup>. Securely anchoring such components, such as thrust bearing removable load shoulders, is necessary to prevent acceleration related galling (Figure 13) and impact damage. Figure 12 shows a used mud motor shaft coated with a bearing lubricant filled with metal particles. The metal particles are the result of too much angular clearance at the anti-rotation feature of the thrust bearing removable load shoulder. This excessive angular clearance created the metal flakes by two mechanisms: Galling between the removable load shoulder and the shaft, and angular impact between the anti-rotation feature and the shaft. Such metal particles in the lubricant may damage the bearings and the rotary shaft seals.

Figure 11 shows an undersized anti-rotation tang of a bearing race that failed due to angular impact resulting from drillstring stick/slip. Anti-rotation features need to be very robust in oilfield downhole drilling tools. Sizing and carefully designing all components to withstand immense G-forces in service is a must.

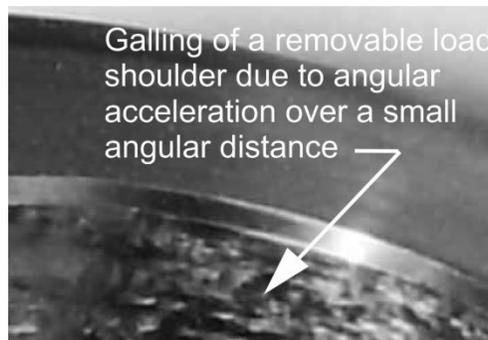
<sup>2</sup> For information on drillstring vibration, see SPE papers 14330, 15560, 15561, 15563, 15564, 145910, 147747, SPE/IADC paper no. 18652, and Erik Skaugen, et al., “**Experimental and Theoretical Studies of Vibrations in Drill Strings Incorporating Shock Absorbers**” (12th World Petroleum Congress, 1987).

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**Figure 12****Metal particles in mud motor seal lubricant due to angular impact**

The metal particles shown here are due to impact between the anti-rotation feature of a thrust bearing removable load shoulder and the mating shaft recess due to high angular acceleration, and due to galling resulting from a slight amount of relative angular motion between the removable shoulder and the shaft. Such metal particles can reduce the life of the bearings and rotary seals.

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**Figure 13****Galling from motion resulting from angular acceleration**

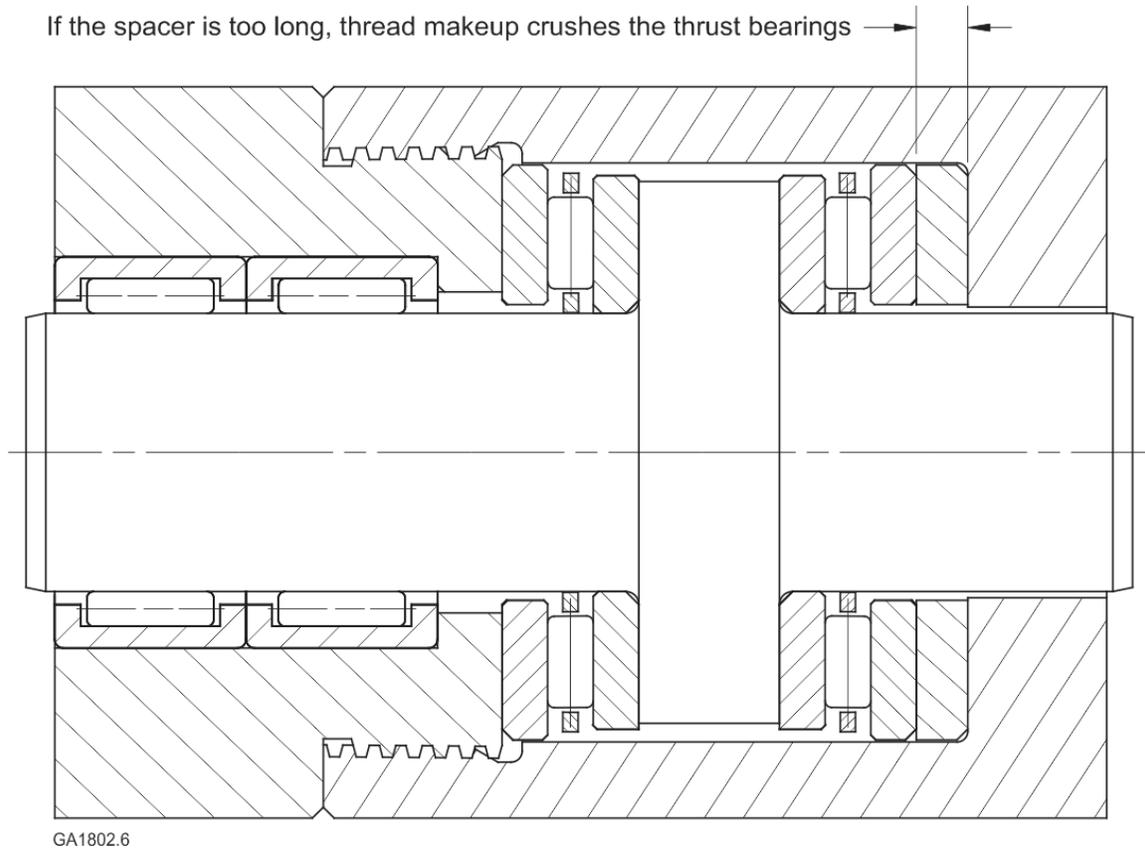
This oilfield mud motor thrust bearing removable load shoulder shows galling due to angular motion relative to the shaft caused by severe angular acceleration. The problem resulted from too much clearance in the anti-rotation feature of the load shoulder.

## 10. Improper spacer length calculation can damage thrust bearings

In some types of tools, such as oilfield mud motor sealed bearing assemblies, a custom length spacer accounts for component tolerance and sets the thrust bearing end clearance (Figure 14). Typically, this involves the following steps:

1. Assemble the tool with an intentionally oversized spacer length, applying just enough thread torque to take up all axial clearance.
2. Measure the gap at the thread shoulder.
3. Calculate the spacer length required to provide the desired end clearance, by subtracting the shoulder gap measurement and the desired end play from the length of the oversized spacer. (The end play is necessary to accommodate differential thermal expansion, measurement error, variations in makeup torque, and variations in friction at the threads and shoulder.)
4. Reassemble the tool with a spacer having the calculated spacer length.

Not considering the axial makeup associated with full assembly torque in this procedure can result in excessive spacer length and crushed thrust bearings. For example, on a mud motor sealed bearing assembly that we designed and tested, 5,000 ft-lb of makeup torque on a 4.1-4 stub acme 2G thread caused about 16.7° motion after the shoulders contacted, using lubricated threads and shoulders. This equates to about 0.012” of axial advancement. Not including this axial advancement when calculating the required spacer length will result in the thrust bearings overloading and in all probability receiving brinelling type damage (Figure 15).



**Figure 14**

**Improper spacer length calculation causes damaged thrust bearings**

In order to avoid crushing the thrust bearings, don't forget to consider the axial motion caused by thread makeup torque when calculating the thrust bearing spacer length.

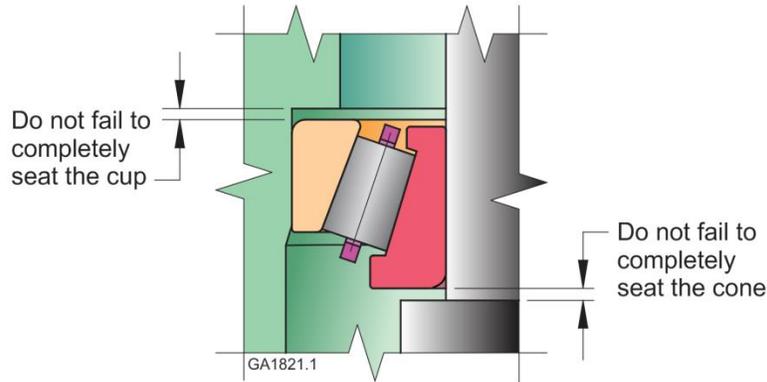


**Figure 15**  
**Brinelling example**

Brinelling of a thrust bearing race occurs due to overload conditions, such as high impact loading or an overload caused by excessive spacer length at the time of assembly.

### **11. Improperly seated bearing cup**

Be sure to seat the cup and cone of a tapered roller bearing securely against their respective mating shoulders (Figure 16). Owing to the roller contact angle, failure to fully seat the cup can lead to a significant increase in shaft runout and deflection, if operating loads cause the cup to move toward the housing shoulder. The increased runout and deflection are detrimental to rotary shaft seal performance. Failure to seat the bearing cone securely against the shaft shoulder will cause the same detrimental loss of accurate shaft guidance. The same is true of spherical roller thrust bearings.



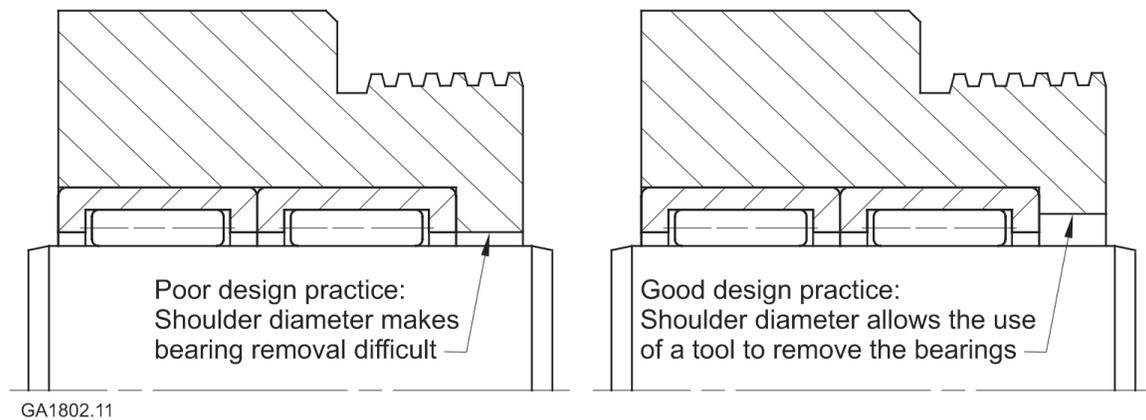
**Figure 16**

**Completely seat tapered roller bearing races**

Failure to completely seat bearing cups or cones can lead to loss of precise radial control when the race position shifts under load, and increases radial clearance. The resulting loss of shaft control can damage the rotary seals, or cause leakage. Special tools are available to facilitate the race seating operation.

**12. Designing shoulders for ease of bearing extraction**

Improper shoulder sizing (Figure 17) can make bearing extraction problematic. When practical, design shaft and housing shoulders that allow use of a tool to extract the bearing. Examples of suitable tools are specially sized sleeves, used in conjunction with a hydraulic press, and conventional bearing pullers.



**Figure 17**

**Don't pick an inconvenient shoulder diameter**

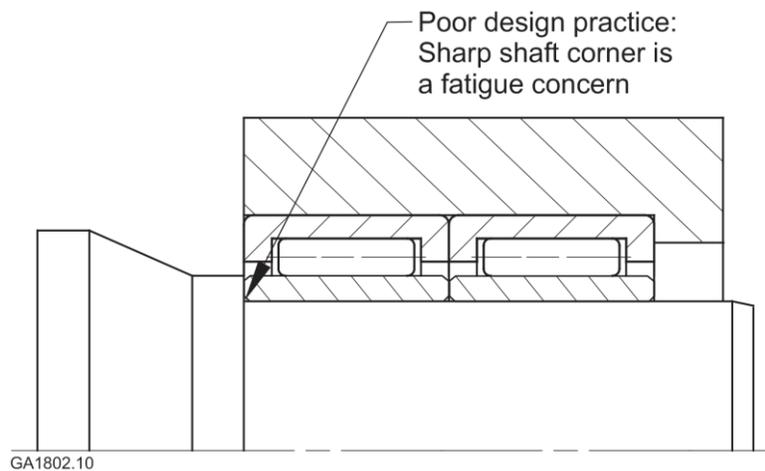
Choose a shoulder diameter that allows use of a tool to extract the bearing.

### 13. Avoid stress risers on rotating shafts

Avoid sharp corners on shafting with side loads. Sharp corners are stress risers that can initiate fatigue failure (Figure 18). In oilfield downhole tools, fatigue failure leads to expensive fishing operations to retrieve the lost part of the shaft.

For information on fatigue failure prediction and prevention, consult engineering handbooks such as:

- Shigley & Mischke, “**Mechanical Engineering Design**”, McGraw-Hill, Inc.
- “**Technical Report on Fatigue Properties**”, SAE J-1099, Society of Automotive Engineers, Inc., 400 Commonwealth Drive, Warrendale, PA 15096, U. S. A.
- Peterson, R. E., “**Stress Concentration Factors**”, John Wiley & Sons, Inc., 1979.
- “**Fatigue Design Handbook**”, Society of Automotive Engineers, Inc., 1968.
- Faupel and Fisher, “**Engineering Design**”, 2nd Edition, John Wiley & Sons, Inc., 1981.
- Barson and Rolfe, “**Fracture & Fatigue Control in Structures**”, 2nd Edition, Prentice-Hall, Inc., 1987.



**Figure 18**

#### **Excessively sharp internal corners on rotary shafts are a fatigue concern**

Excessively sharp corners on rotating shafts are a fatigue concern. They create stress risers that promote fatigue cracks, which can eventually lead to complete failure of the shaft.

#### 14. Inadequate lubricant viscosity

In heavily loaded equipment, such as oilfield mud motors, the bearings require adequate lubricant viscosity; consult the bearing manufacturer for recommendations. Inadequate lubricant viscosity can cause bearings to fail prematurely. Be sure to consider the adequacy of the viscosity at the upper end of the equipment operating temperature range. Consult the Catalog & Technical Data section of this handbook to evaluate the impact a lubricant change will have on the hydrodynamic pumping related leakage of the Kalsi Seals.

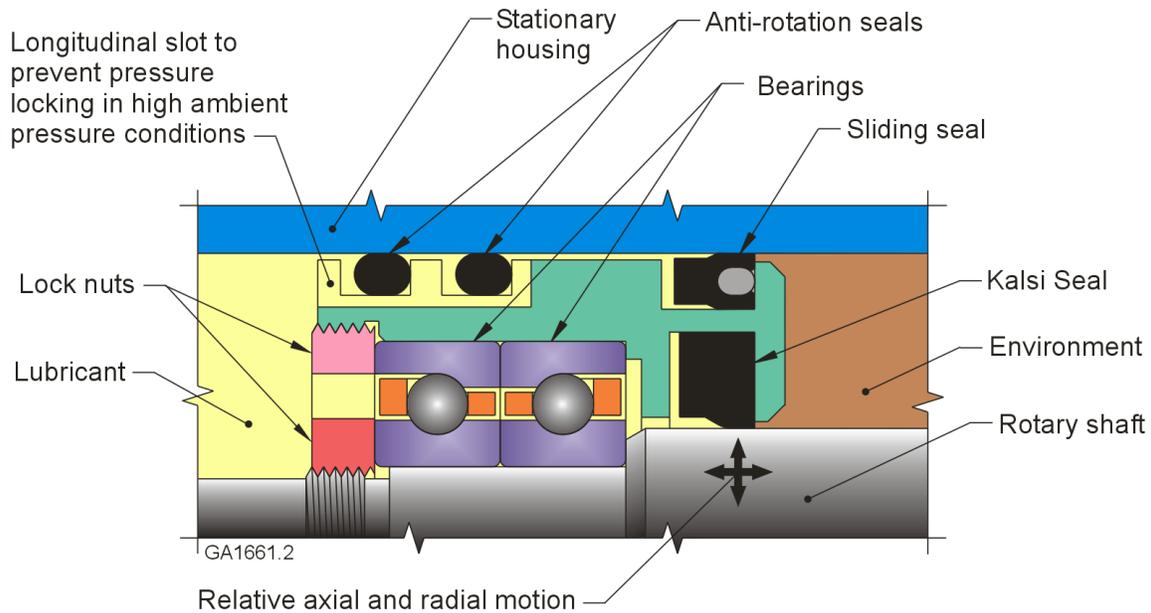
#### 15. Pressure-related thrust

In equipment where differential pressure acts over the sealed area(s) of a shaft, do not forget to take the pressure-related thrust load into account when sizing the thrust bearings.

#### 16. Orientation of angular contact bearings

The various ways that angular contact ball bearings can be employed is beyond the scope of this rotary seal handbook. Nevertheless, it is worth pointing out that the orientation of such bearings is critical. For example, in Figure 19 a set of angular contact bearings are clamped in a “*back-to-back*” arrangement, to provide thrust capacity in both directions, and to resist moments that would tend to make the seal carrier rock with respect to the rotary shaft. If the bearings were accidentally installed in a “*face-to-face*” arrangement, the bearings would still provide thrust capacity in both directions, but the resistance to moments would be greatly diminished, and seal carrier would be more prone to rocking relative to the shaft. If the bearings were accidentally installed so that both were facing the same direction, the resistance to moments would be diminished, and thrust capacity would only be present in one direction. It is critical to train your mechanics to install angular contact bearings in the intended orientation, and it is equally critical to make sure that the machine designer picks an appropriate bearing orientation.

In Figure 5, the angular contact bearings are installed in a “*face-to-face*” arrangement, to purposely minimize resistance to moments. This makes it less likely that the angular contact bearings will bind with respect to the left-hand radial bearing in the event that the bore for the angular contact bearings is misaligned with respect to the bore for the left-hand radial bearing.



**Figure 19**

**Orientation of angular contact bearings matters**

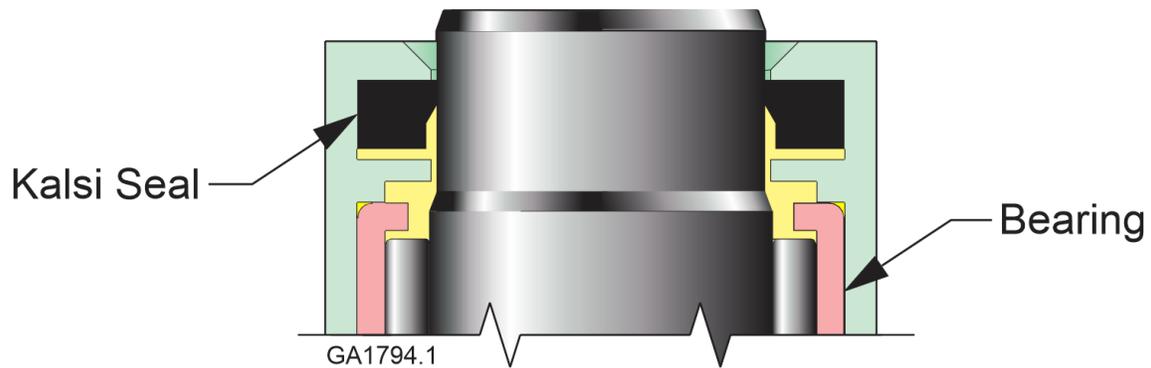
In this arrangement, angular contact bearings are mounted “*back-to-back*”, to provide resistance to moments, so that the seal carrier does not rock with respect to the rotary shaft. If the bearings are inadvertently installed “*face-to-face*”, much of the resistance to moments is lost. Either the “*back-to-back*” or “*face-to-face*” orientation provides thrust capability in both directions. If both bearings are oriented in the same direction (“*tandem*”), thrust capacity is present only in one direction, and resistance to moments is significantly diminished.

**17. Bearing availability**

Check availability before finalizing bearing selection. Many cataloged bearings are not readily available, and have prohibitively long manufacturing lead times.

### 18. Seal considerations related to the bearing implementation

To achieve the best concentricity between the shaft and the seal groove and between the shaft and the seal housing bore that defines the extrusion gap with the shaft, place the radial bearing that guides the shaft in the seal housing (Figure 20). To prevent the bearing from scoring the seal running surface during bearing installation onto the shaft, make the diameter of the seal running surface slightly smaller than the diameter of the shaft that mates with the bearing (Figure 20). To minimize shaft deflection at the rotary seal, place the radial bearing close to the rotary seal (Figure 20).



**Figure 20**

#### **Seal considerations**

For the best concentricity between the seal housing and the shaft, locate the radial bearing in the seal housing. Place the seal groove close to the radial bearing to minimize shaft deflection at the rotary seal location. To protect the seal running surface from bearing installation damage, make the running surface smaller than the shaft surface that mates with the bearing.